

A Unifying Generative Model for Graph Learning Algorithms

Authors: Junteng Jia and Austin R. Benson

Presenter: Sudhanshu Chanpuriya

Setting

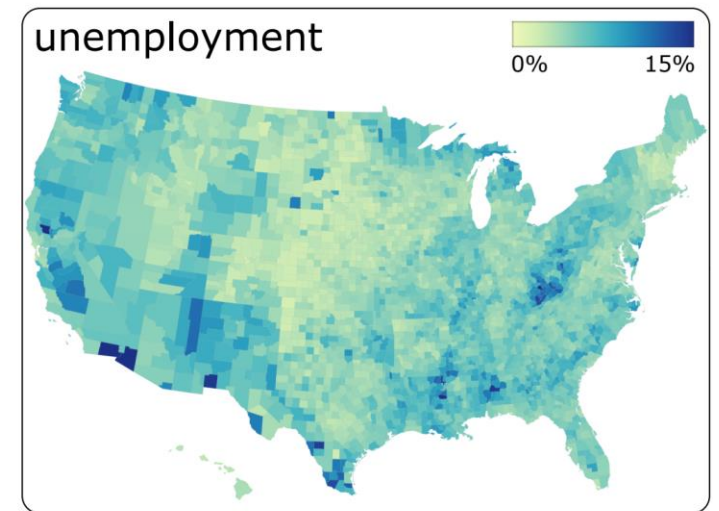
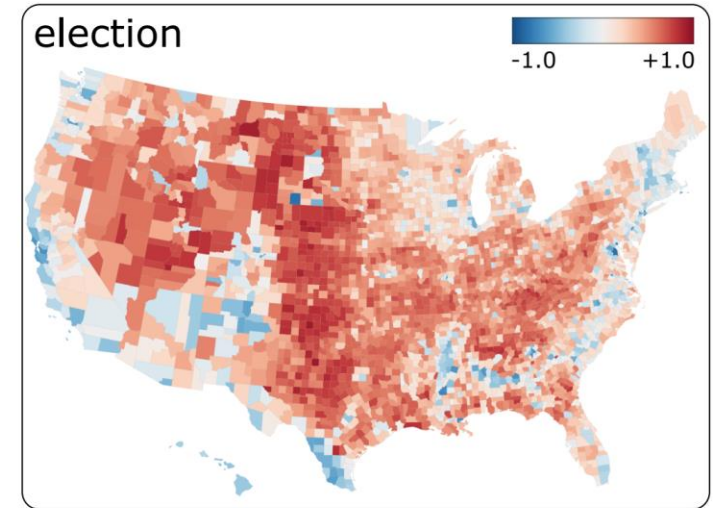
Graph	$G = (V, E)$
Weighted adjacency matrix	$\mathbf{W} \in \mathbb{R}^{n \times n}$
Degree matrix	$\mathbf{D} = \text{diag}(\mathbf{W}\mathbf{1}) \in \mathbb{R}^{n \times n}$
Symmetric normed adj. matrix	$\mathbf{S} = \mathbf{D}^{-1/2} \mathbf{W} \mathbf{D}^{-1/2} \in \mathbb{R}^{n \times n}$
Normalized Laplacian	$\mathbf{N} = \mathbf{I} - \mathbf{S} \in \mathbb{R}^{n \times n}$

Setting

Graph	$G = (V, E)$
Weighted adjacency matrix	$\mathbf{W} \in \mathbb{R}^{n \times n}$
Degree matrix	$\mathbf{D} = \text{diag}(\mathbf{W}\mathbf{1}) \in \mathbb{R}^{n \times n}$
Symmetric normed adj. matrix	$\mathbf{S} = \mathbf{D}^{-1/2}\mathbf{W}\mathbf{D}^{-1/2} \in \mathbb{R}^{n \times n}$
Normalized Laplacian	$\mathbf{N} = \mathbf{I} - \mathbf{S} \in \mathbb{R}^{n \times n}$
Feature matrix	$\mathbf{X} \in \mathbb{R}^{n \times p}$
Label vector	$\mathbf{y} \in \mathbb{R}^n$
Attribute matrix	$\mathbf{A} = [\mathbf{X} \ \mathbf{y}] \in \mathbb{R}^{n \times (p+1)}$
Labeled nodes	$L \in V$
Unlabeled nodes	$U = V \setminus L \in V$

Setting

Graph	$G = (V, E)$
Adjacency	$W \in \mathbb{R}^{n \times n}$
Degree	$D = \text{diag}(W\mathbf{1}) \in \mathbb{R}^{n \times n}$
Normed adj.	$S = D^{-1/2}WD^{-1/2} \in \mathbb{R}^{n \times n}$
Laplacian	$N = I - S \in \mathbb{R}^{n \times n}$
Feature	$X \in \mathbb{R}^{n \times p}$
Label	$y \in \mathbb{R}^n$
Attribute	$A = [X \ y] \in \mathbb{R}^{n \times (p+1)}$
Labeled	$L \in V$
Unlabeled	$U = V \setminus L \in V$



⋮

other attributes

Setting

Graph	$G = (V, E)$
Weighted adjacency matrix	$\mathbf{W} \in \mathbb{R}^{n \times n}$
Degree matrix	$\mathbf{D} = \text{diag}(\mathbf{W}\mathbf{1}) \in \mathbb{R}^{n \times n}$
Symmetric normed adj. matrix	$\mathbf{S} = \mathbf{D}^{-1/2}\mathbf{W}\mathbf{D}^{-1/2} \in \mathbb{R}^{n \times n}$
Normalized Laplacian	$\mathbf{N} = \mathbf{I} - \mathbf{S} \in \mathbb{R}^{n \times n}$
Feature matrix (zero-centered)	$\mathbf{X} \in \mathbb{R}^{n \times p}$
Label vector (zero-centered)	$\mathbf{y} \in \mathbb{R}^n$
Attribute matrix (zero-centered)	$\mathbf{A} = [\mathbf{X} \ \mathbf{y}] \in \mathbb{R}^{n \times (p+1)}$
Labeled nodes	$L \in V$
Unlabeled nodes	$U = V \setminus L \in V$

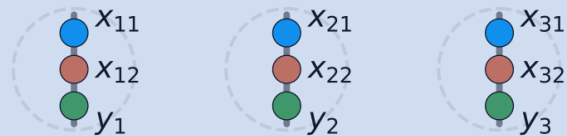
Data Type

Corresponding Gaussian MRF

Learning Algorithm



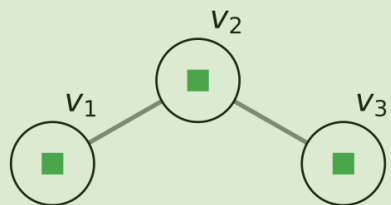
i.i.d. data (\mathbf{X}, \mathbf{y})



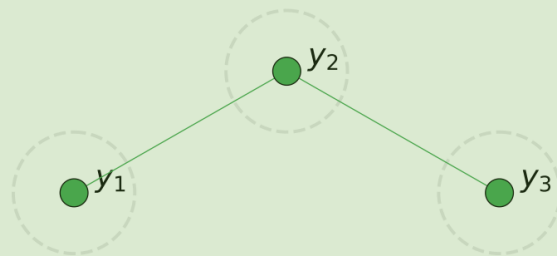
condition on \mathbf{X}
e.g. $L=\{1,3\}, U=\{2\}$

linear regression

$$E[\mathbf{y}_U|\mathbf{X}] = \mathbf{X}_U\boldsymbol{\beta} \quad \boldsymbol{\beta} = (\mathbf{X}_L^T\mathbf{X}_L)^{-1}\mathbf{X}_L^T\mathbf{y}_L$$



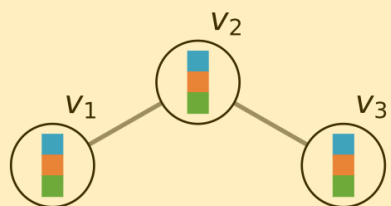
graph data (\mathbf{y}, G)



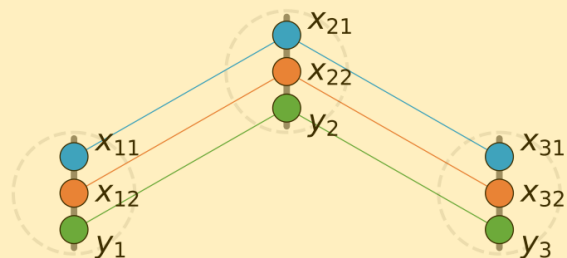
condition on \mathbf{y}_L

label propagation

$$E[\mathbf{y}_U|\mathbf{y}_L] = -(\mathbf{I} + \omega\mathbf{N})_{UU}^{-1}(\mathbf{I} + \omega\mathbf{N})_{UL}\mathbf{y}_L$$



graph data $(\mathbf{X}, \mathbf{y}, G)$



condition on \mathbf{X}

linear GC

$$E[\mathbf{y}_U|\mathbf{X}] = [(\mathbf{I} + \omega\mathbf{N})^{-1}\mathbf{X}\boldsymbol{\beta}]_U$$

further condition on \mathbf{y}_L

residual propagation

$$E[\mathbf{y}_U|\mathbf{X}, \mathbf{y}_L] = \dots$$

change filter

SGC (simple graph convolution)

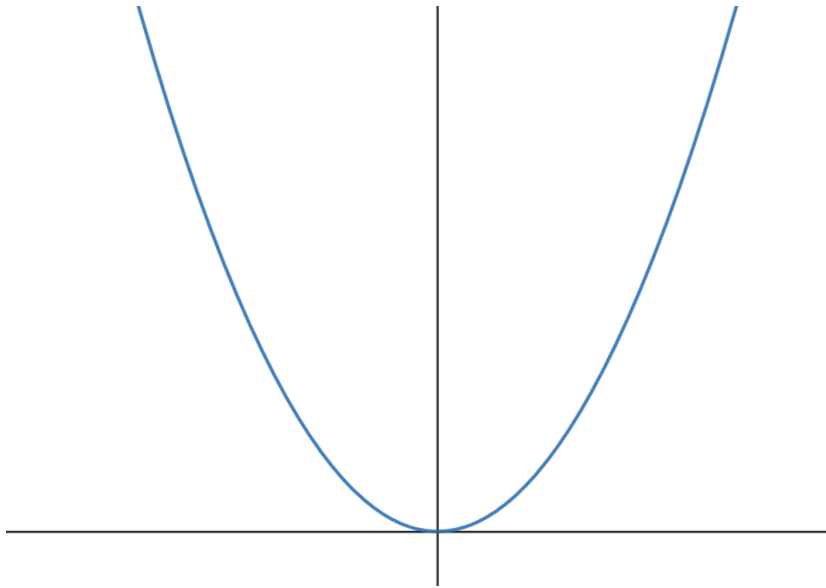
+nonlinearity

GCN (graph convolution network)

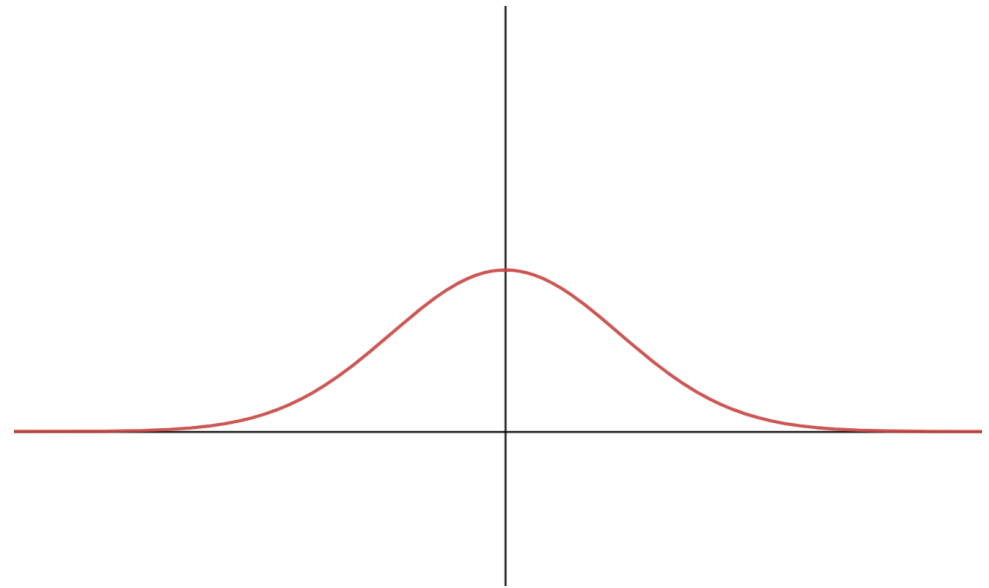
Outline

1. Prerequisites
 - a. Normal distributions
 - b. Marginalizing and conditioning normals
2. Unifying model
3. Deriving learning algorithms
 - a. Linear regression
 - b. Label propagation
 - c. Graph convolution

Normal Distribution

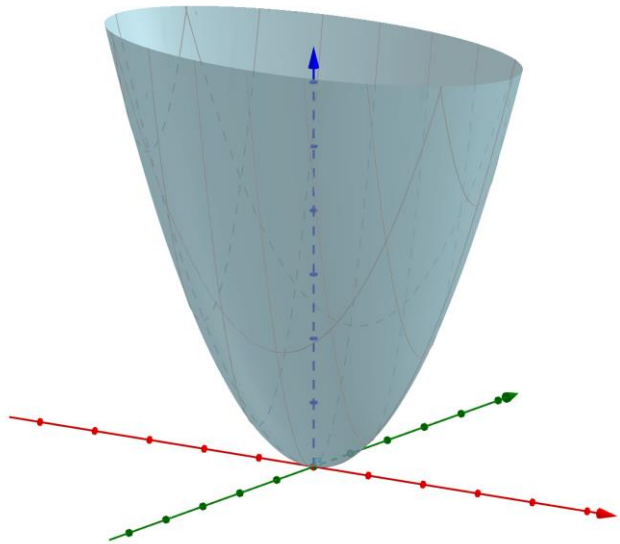


$$\begin{aligned}\phi(x) &= \gamma x^2 = x\gamma x \\ \gamma &> 0\end{aligned}$$

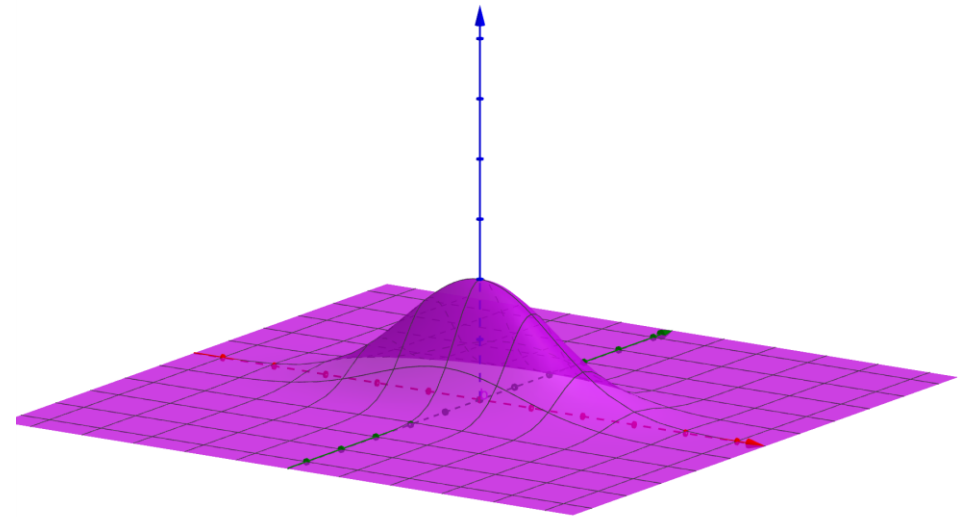


$$\begin{aligned}\rho(x) &\propto e^{-\phi(x)} = e^{-x\gamma x} \\ \gamma &= 1/\sigma^2\end{aligned}$$

Normal Distribution



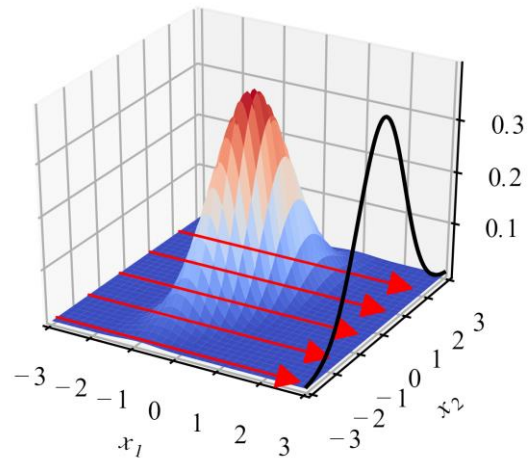
$$\begin{aligned}\phi(\mathbf{x}) &= \mathbf{x}^\top \mathbf{\Gamma} \mathbf{x} \\ \mathbf{\Gamma} &\succcurlyeq 0\end{aligned}$$



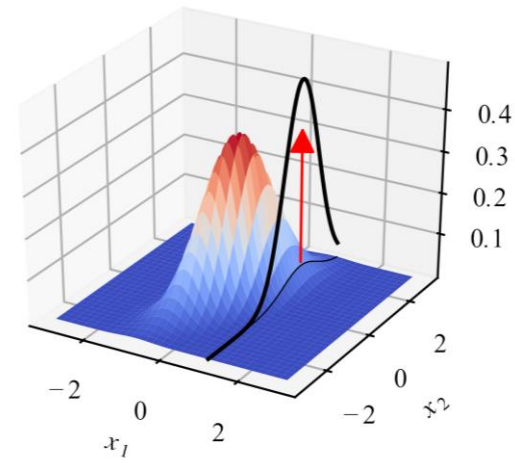
$$\begin{aligned}\rho(\mathbf{x}) &\propto e^{-\phi(\mathbf{x})} = e^{-\mathbf{x}^\top \mathbf{\Gamma} \mathbf{x}} \\ \mathbf{\Gamma} &= \mathbf{\Sigma}^{-1}\end{aligned}$$

Marginalizing and Conditioning Normals

$$\begin{pmatrix} \mathbf{z}_P \\ \mathbf{z}_Q \end{pmatrix} \sim \mathcal{N} \left(\begin{bmatrix} \bar{\mathbf{z}}_P \\ \bar{\mathbf{z}}_Q \end{bmatrix}, \begin{bmatrix} \Sigma_{PP} & \Sigma_{PQ} \\ \Sigma_{QP} & \Sigma_{QQ} \end{bmatrix} \right)$$



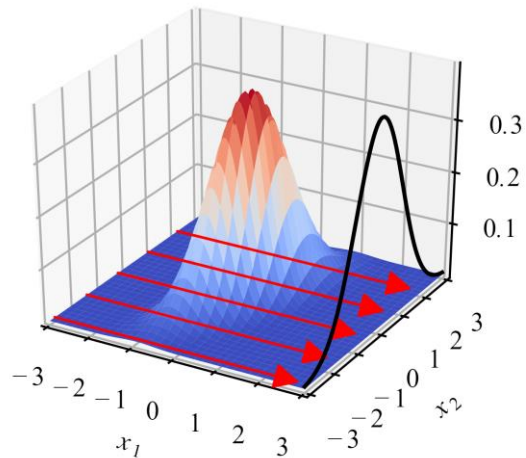
Marginalizing



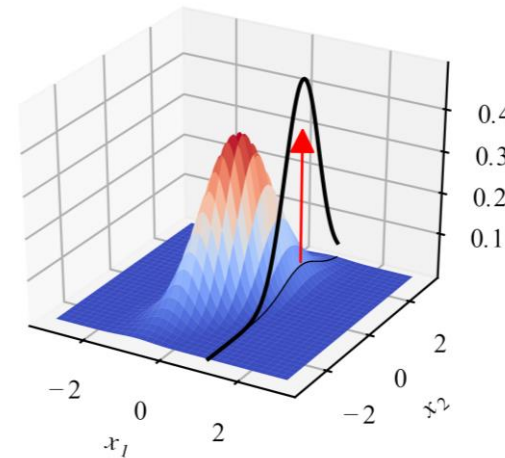
Conditioning

Marginalizing and Conditioning Normals

$$\begin{pmatrix} \mathbf{z}_P \\ \mathbf{z}_Q \end{pmatrix} \sim \mathcal{N} \left(\begin{bmatrix} \bar{\mathbf{z}}_P \\ \bar{\mathbf{z}}_Q \end{bmatrix}, \begin{bmatrix} \Sigma_{PP} & \Sigma_{PQ} \\ \Sigma_{QP} & \Sigma_{QQ} \end{bmatrix} \right)$$



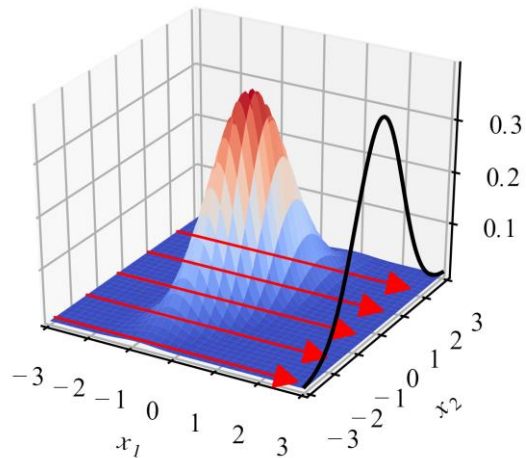
Marginalizing
 $\mathbf{z}_P \sim \mathcal{N}(\bar{\mathbf{z}}_P, \Sigma_{PP})$



Conditioning
 $\mathbf{z}_P | \mathbf{z}_Q \sim \mathcal{N}(\bar{\mathbf{z}}_P + \Sigma_{PQ} \Sigma_{QQ}^{-1} (\mathbf{z}_Q - \bar{\mathbf{z}}_Q), \Sigma_{PP} - \Sigma_{PQ} \Sigma_{QQ}^{-1} \Sigma_{QP})$

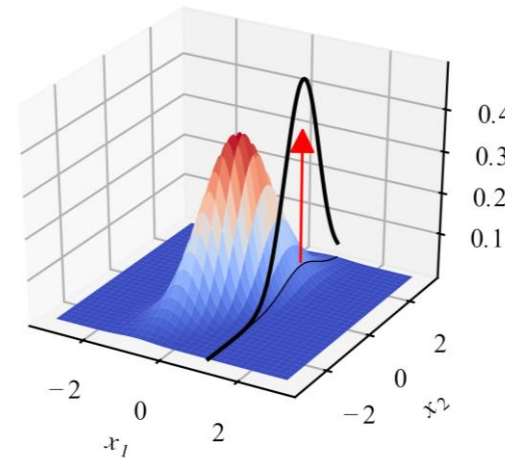
Marginalizing and Conditioning Normals

$$\begin{pmatrix} \mathbf{z}_P \\ \mathbf{z}_Q \end{pmatrix} \sim \mathcal{N} \left(\begin{bmatrix} \bar{\mathbf{z}}_P \\ \bar{\mathbf{z}}_Q \end{bmatrix}, \begin{bmatrix} \Gamma_{PP} & \Gamma_{PQ} \\ \Gamma_{QP} & \Gamma_{QQ} \end{bmatrix}^{-1} \right)$$



Marginalizing

$$\mathbf{z}_P \sim \mathcal{N} \left(\bar{\mathbf{z}}_P, (\Gamma_{PP} - \Gamma_{PQ} \Gamma_{QQ}^{-1} \Gamma_{QP})^{-1} \right)$$



Conditioning

$$\mathbf{z}_P | \mathbf{z}_Q \sim \mathcal{N} \left(\bar{\mathbf{z}}_P - \Gamma_{PP}^{-1} \Gamma_{PQ} (\mathbf{z}_Q - \bar{\mathbf{z}}_Q), \Gamma_{PP}^{-1} \right)$$

Unifying Model

Distribution over attribute matrix:

$$\rho(\mathbf{A} = \mathbf{A} | \mathbf{H}, \mathbf{h}) \propto e^{-\phi(\mathbf{A} | \mathbf{H}, \mathbf{h})}$$

- $\mathbf{H} \in \mathbb{R}^{(p+1) \times (p+1)}$ is positive definite
- $\mathbf{h} \in \mathbb{R}^{(p+1)}$ is entrywise positive

$$\phi(\mathbf{A} | \mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

Unifying Model

Distribution over attribute matrix:

$$\rho(\mathbf{A} = \mathbf{A} | \mathbf{H}, \mathbf{h}) \propto e^{-\phi(\mathbf{A} | \mathbf{H}, \mathbf{h})}$$

- $\mathbf{H} \in \mathbb{R}^{(p+1) \times (p+1)}$ is positive definite
- $\mathbf{h} \in \mathbb{R}^{(p+1)}$ is entrywise positive

$$\phi(\mathbf{A} | \mathbf{H}, \mathbf{h}) = \underbrace{\frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u}_{\text{Correlations among attributes in each node}} + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

Correlations among
attributes in each node

Unifying Model

Distribution over attribute matrix:

$$\rho(\mathbf{A} = \mathbf{A} | \mathbf{H}, \mathbf{h}) \propto e^{-\phi(\mathbf{A} | \mathbf{H}, \mathbf{h})}$$

- $\mathbf{H} \in \mathbb{R}^{(p+1) \times (p+1)}$ is positive definite
- $\mathbf{h} \in \mathbb{R}^{(p+1)}$ is entrywise positive

$$\phi(\mathbf{A} | \mathbf{H}, \mathbf{h}) = \underbrace{\frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u}_{\text{Correlations among attributes in each node}} + \underbrace{\frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i}_{\text{Discourage roughness of each attribute over graph}}$$

Correlations among attributes in each node


Discourage roughness of each attribute over graph

$$\mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i = \sum_{(u,v) \in E} \left(\frac{A_{ui}}{\sqrt{d_u}} - \frac{A_{vi}}{\sqrt{d_v}} \right)^2$$


Data Type

Corresponding Gaussian MRF

Learning Algorithm



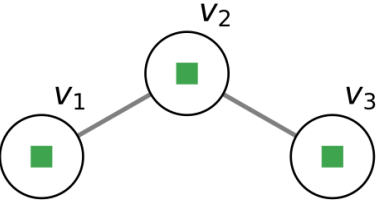
 i.i.d. data (\mathbf{X}, \mathbf{y})



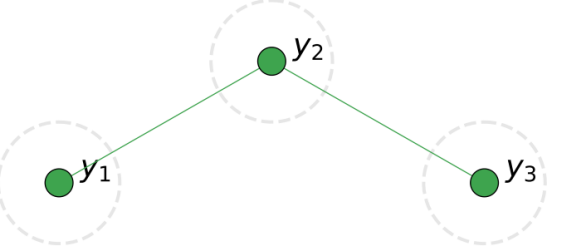
 X_{11}, X_{12}, y_1 X_{21}, X_{22}, y_2 X_{31}, X_{32}, y_3

$\xrightarrow[\text{e.g. } L=\{1,3\}, U=\{2\}]{\text{condition on } \mathbf{X}}$

linear regression
 $E[\mathbf{y}_U | \mathbf{X}] = \mathbf{X}_U \boldsymbol{\beta}$ $\boldsymbol{\beta} = (\mathbf{X}_L^T \mathbf{X}_L)^{-1} \mathbf{X}_L^T \mathbf{y}_L$

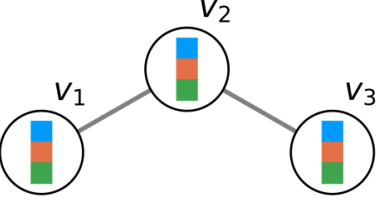


 graph data (\mathbf{y}, G)

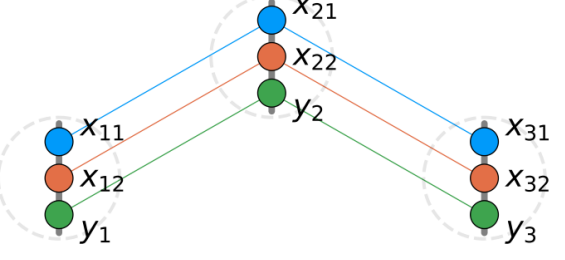


$\xrightarrow{\text{condition on } \mathbf{y}_L}$

label propagation
 $E[\mathbf{y}_U | \mathbf{y}_L] = -(\mathbf{I} + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I} + \omega \mathbf{N})_{UL} \mathbf{y}_L$



 graph data $(\mathbf{X}, \mathbf{y}, G)$



$\xrightarrow{\text{condition on } \mathbf{X}}$

linear GC $\xrightarrow{\text{further condition on } \mathbf{y}_L}$ **residual propagation**
 $E[\mathbf{y}_U | \mathbf{X}] = [(\mathbf{I} + \omega \mathbf{N})^{-1} \mathbf{X} \boldsymbol{\beta}]_U$ $E[\mathbf{y}_U | \mathbf{X}, \mathbf{y}_L] = \dots$

\downarrow change filter
SGC (simple graph convolution)

\downarrow +nonlinearity
GCN (graph convolution network)

Edgeless Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

Edgeless Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\begin{aligned} \rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) &= \frac{e^{-\frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u}}{\int d\mathbf{A}' e^{-\frac{1}{2} \sum_{u=1}^n \mathbf{a}'_u{}^\top \mathbf{H} \mathbf{a}'_u}} \\ &= \prod_{u=1}^n \frac{e^{-\frac{1}{2} \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u}}{\int d\mathbf{a}'_u e^{-\frac{1}{2} \mathbf{a}'_u{}^\top \mathbf{H} \mathbf{a}'_u}} \\ &\propto \prod_{u=1}^n e^{-\frac{1}{2} \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u} . \end{aligned}$$

Edgeless Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\begin{aligned} \rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) &= \frac{e^{-\frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u}}{\int d\mathbf{A}' e^{-\frac{1}{2} \sum_{u=1}^n \mathbf{a}'_u{}^\top \mathbf{H} \mathbf{a}'_u}} \\ &= \prod_{u=1}^n \frac{e^{-\frac{1}{2} \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u}}{\int d\mathbf{a}' e^{-\frac{1}{2} \mathbf{a}'^\top \mathbf{H} \mathbf{a}'}} \\ &\propto \prod_{u=1}^n e^{-\frac{1}{2} \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u} . \end{aligned}$$

ρ decomposes into a product of n IID normals, one for each node, with mean 0 and precision H .

Edgeless Case: Conditioning

The rows $\{\mathbf{a}_u\}_{u=1}^n$ of the attribute matrix are IID normals with mean 0, precision H .

Now condition on the features \mathbf{X} to find the expectation of the labels \mathbf{y} :

$$\text{For each node } u \in V, \mathbb{E}[y_u | \mathbf{X} = \mathbf{X}] = \underbrace{\mathbb{E}[y_u | \mathbf{x}_u = \mathbf{x}_u]}$$

Condition on p out
of $p + 1$ attributes

Edgeless Case: Conditioning

The rows $\{\mathbf{a}_u\}_{u=1}^n$ of the attribute matrix are IID normals with mean 0, precision H .

Now condition on the features \mathbf{X} to find the expectation of the labels \mathbf{y} :

For each node $u \in V$, $\mathbb{E}[y_u | \mathbf{X} = \mathbf{X}] = \mathbb{E}[y_u | \mathbf{x}_u = \mathbf{x}_u] = \mathbf{x}_u^\top \left(\frac{-\mathbf{H}_{1:p,p+1}}{H_{p+1,p+1}} \right)$.

$\mathbb{E}[\mathbf{y} | \mathbf{X} = \mathbf{X}] = \mathbf{X}\boldsymbol{\beta}$ for $\boldsymbol{\beta} = \frac{-\mathbf{H}_{1:p,p+1}}{H_{p+1,p+1}} \in \mathbb{R}^p$.

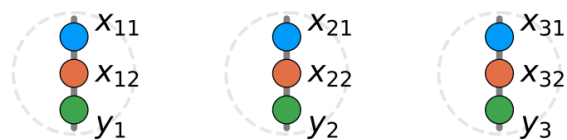
Algorithm: Rather than finding \mathbf{H} , fit $\boldsymbol{\beta}$ directly via linear regression on known labels $(\mathbf{X}_L, \mathbf{y}_L)$.

Data Type



i.i.d. data (\mathbf{X}, \mathbf{y})

Corresponding Gaussian MRF



condition on \mathbf{X}
e.g. $L=\{1,3\}, U=\{2\}$

Learning Algorithm

linear regression

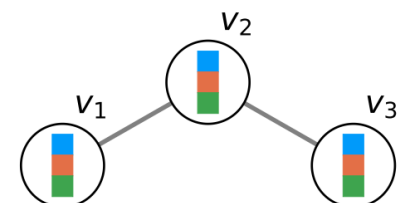
$$E[\mathbf{y}_U | \mathbf{X}] = \mathbf{X}_U \boldsymbol{\beta} \quad \boldsymbol{\beta} = (\mathbf{X}_L^T \mathbf{X}_L)^{-1} \mathbf{X}_L^T \mathbf{y}_L$$

graph data (\mathbf{y}, G)

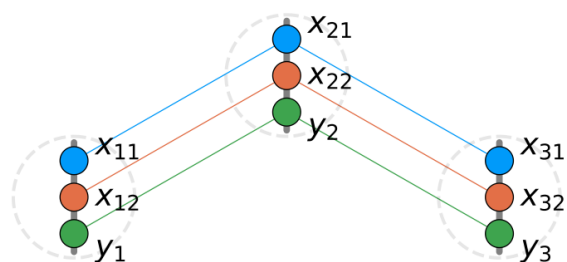
condition on \mathbf{y}_L

label propagation

$$E[\mathbf{y}_U | \mathbf{y}_L] = -(\mathbf{I} + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I} + \omega \mathbf{N})_{UL} \mathbf{y}_L$$



graph data $(\mathbf{X}, \mathbf{y}, G)$



condition on \mathbf{X}

linear GC

$$E[\mathbf{y}_U | \mathbf{X}] = [(\mathbf{I} + \omega \mathbf{N})^{-1} \mathbf{X} \boldsymbol{\beta}]_U$$

change filter

SGC (simple graph convolution)

+nonlinearity

GCN (graph convolution network)

further condition on \mathbf{y}_L

residual propagation

$$E[\mathbf{y}_U | \mathbf{X}, \mathbf{y}_L] = \dots$$

Featureless Case

General model:

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

Without features ($p = 0$):

$$\phi(\mathbf{y}|H, h) = \frac{1}{2} \sum_{u=1}^n y_u H y_u + \frac{1}{2} h \mathbf{y}^\top \mathbf{N} \mathbf{y}$$

Featureless Case

General model:

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

Without features ($p = 0$):

$$\begin{aligned} \phi(\mathbf{y}|H, h) &= \frac{1}{2} \sum_{u=1}^n y_u H y_u + \frac{1}{2} h \mathbf{y}^\top \mathbf{N} \mathbf{y} \\ &= \frac{1}{2} H \mathbf{y}^\top \mathbf{I}_n \mathbf{y} + \frac{1}{2} h \mathbf{y}^\top \mathbf{N} \mathbf{y} \\ &= \frac{1}{2} \mathbf{y}^\top (H \mathbf{I}_n + h \mathbf{N}) \mathbf{y} = \frac{1}{2} \mathbf{y}^\top \mathbf{\Gamma} \mathbf{y}, \text{ where } \mathbf{\Gamma} = H \mathbf{I}_n + h \mathbf{N}. \end{aligned}$$

Featureless Case: Conditioning

$$\rho(\mathbf{y} = \mathbf{y} | H, h) = e^{-\frac{1}{2} \mathbf{y}^\top \mathbf{\Gamma} \mathbf{y}}, \text{ where } \mathbf{\Gamma} = H \mathbf{I}_n + h \mathbf{N}.$$

Now condition on known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U :

Featureless Case: Conditioning

$$\rho(\mathbf{y} = \mathbf{y} | H, h) = e^{-\frac{1}{2} \mathbf{y}^\top \mathbf{\Gamma} \mathbf{y}}, \text{ where } \mathbf{\Gamma} = H \mathbf{I}_n + h \mathbf{N}.$$

Now condition on known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U :

$$\begin{aligned} \mathbb{E}[\mathbf{y}_U | \mathbf{y}_L = \mathbf{y}_L] &= -\mathbf{\Gamma}_{UU}^{-1} \mathbf{\Gamma}_{UL} \mathbf{y}_L \\ &= -(\mathbf{H} \mathbf{I}_n + h \mathbf{N})_{UU}^{-1} (\mathbf{H} \mathbf{I}_n + h \mathbf{N})_{UL} \mathbf{y}_L \\ &= -(\mathbf{I}_n + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I}_n + \omega \mathbf{N})_{UL} \mathbf{y}_L, \text{ where } \omega = h/H. \end{aligned}$$

Featureless Case: Conditioning

$$\rho(\mathbf{y} = \mathbf{y} | H, h) = e^{-\frac{1}{2} \mathbf{y}^\top \mathbf{\Gamma} \mathbf{y}}, \text{ where } \mathbf{\Gamma} = H \mathbf{I}_n + h \mathbf{N}.$$

Now condition on known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U :

$$\mathbb{E}[\mathbf{y}_U | \mathbf{y}_L = \mathbf{y}_L] = -(\mathbf{I}_n + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I}_n + \omega \mathbf{N})_{UL} \mathbf{y}_L, \text{ where } \omega = h/H.$$

Featureless Case: Conditioning

$$\rho(\mathbf{y} = \mathbf{y} | H, h) = e^{-\frac{1}{2} \mathbf{y}^\top \Gamma \mathbf{y}}, \text{ where } \Gamma = H \mathbf{I}_n + h \mathbf{N}.$$

Now condition on known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U :

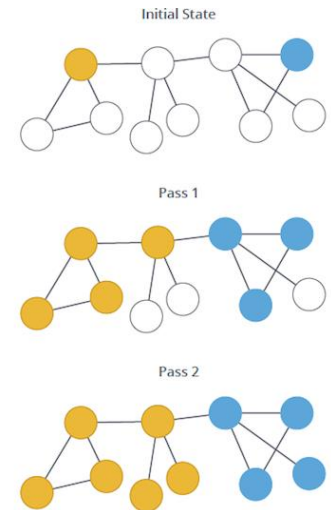
$$\mathbb{E}[\mathbf{y}_U | \mathbf{y}_L = \mathbf{y}_L] = -(\mathbf{I}_n + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I}_n + \omega \mathbf{N})_{UL} \mathbf{y}_L, \text{ where } \omega = h/H.$$

Algorithm: Label propagation.

$$\forall u \in L, y_u^{(0)} = y_u \text{ and } y_u^{(t+1)} = y_u^{(t)},$$

$$\forall u \in U, y_u^{(0)} = 0 \text{ and } y_u^{(t+1)} = (1 - \alpha) y_u^{(0)} + \alpha d_u^{-1/2} \sum_{v \in N_1(u)} d_v^{-1/2} y_v^{(t)},$$

where $\alpha = \frac{\omega}{1+\omega} \in (0,1)$ and $N_1(u)$ are the neighbors of u .



Featureless Case: Conditioning

$$p(\mathbf{y} = \mathbf{y} | H, h) = e^{-\frac{1}{2} \mathbf{y}^\top \Gamma \mathbf{y}}, \text{ where } \Gamma = H \mathbf{I}_n + h \mathbf{N}.$$

Now condition on known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U :

$$\mathbb{E}[\mathbf{y}_U | \mathbf{y}_L = \mathbf{y}_L] = -(\mathbf{I}_n + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I}_n + \omega \mathbf{N})_{UL} \mathbf{y}_L, \text{ where } \omega = h/H.$$

Algorithm: Label propagation.

$$\forall u \in L, y_u^{(0)} = y_u \text{ and } y_u^{(t+1)} = y_u^{(t)},$$

$$\forall u \in U, y_u^{(0)} = 0 \text{ and } y_u^{(t+1)} = (1 - \alpha) y_u^{(0)} + \alpha d_u^{-1/2} \sum_{v \in N_1(u)} d_v^{-1/2} y_v^{(t)},$$

where $\alpha = \frac{\omega}{1+\omega} \in (0,1)$ and $N_1(u)$ are the neighbors of u .



Equivalent?

Featureless Case: Label Prop Proof

Vectorized form of iteration

$$\forall u \in L, y_u^{(0)} = y_u \text{ and } y_u^{(t+1)} = y_u^{(t)}$$

$$\forall u \in U, y_u^{(0)} = 0 \text{ and } y_u^{(t+1)} = (1 - \alpha)y_u^{(0)} + \alpha d_u^{-1/2} \sum_{v \in N_1(u)} d_v^{-1/2} y_v^{(t)}.$$

$$\begin{aligned} \mathbf{y}_U^{(t+1)} &= (1 - \alpha)\mathbf{y}_U^{(0)} + \alpha \mathbf{S}_{U, U \cup L} \mathbf{y}^{(t)} \\ &= (1 - \alpha)\mathbf{y}_U^{(0)} + \alpha (\mathbf{S}_{UU} \mathbf{y}_U^{(t)} + \mathbf{S}_{UL} \mathbf{y}_L^{(t)}) \\ &= \alpha \mathbf{S}_{UU} \mathbf{y}_U^{(t)} + \alpha \mathbf{S}_{UL} \mathbf{y}_L. \end{aligned}$$

Featureless Case: Label Prop Proof

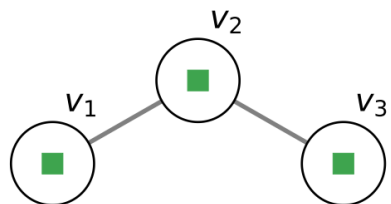
Fixed point of iteration $\mathbf{y}_U^{(t+1)} = \alpha \mathbf{S}_{UU} \mathbf{y}_U^{(t)} + \alpha \mathbf{S}_{UL} \mathbf{y}_L$.

$$\begin{aligned} \mathbf{y}_U^{(\infty)} &= \alpha \mathbf{S}_{UU} \mathbf{y}_U^{(\infty)} + \alpha \mathbf{S}_{UL} \mathbf{y}_L \\ &= (\mathbf{I} - \alpha \mathbf{S})_{UU}^{-1} (\alpha \mathbf{S}_{UL}) \mathbf{y}_L \\ &= -(\mathbf{I} - \alpha \mathbf{S})_{UU}^{-1} (-\alpha \mathbf{S}_{UL}) \mathbf{y}_L \\ &= -(\mathbf{I} - \alpha \mathbf{S})_{UU}^{-1} (\mathbf{I} - \alpha \mathbf{S})_{UL} \mathbf{y}_L \\ &= -\left((1 - \alpha) \mathbf{I} + \alpha \mathbf{I} - \alpha \mathbf{S} \right)_{UU}^{-1} \left((1 - \alpha) \mathbf{I} + \alpha \mathbf{I} - \alpha \mathbf{S} \right)_{UL} \mathbf{y}_L \\ &= -\left(\mathbf{I} + \frac{\alpha}{1 - \alpha} (\mathbf{I} - \mathbf{S}) \right)_{UU}^{-1} \left(\mathbf{I} + \frac{\alpha}{1 - \alpha} (\mathbf{I} - \mathbf{S}) \right)_{UL} \mathbf{y}_L \\ &= -(\mathbf{I} + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I} + \omega \mathbf{N})_{UL} \mathbf{y}_L. \end{aligned}$$

Data Type

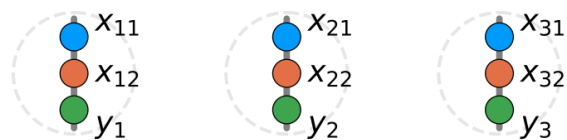


i.i.d. data (\mathbf{X}, \mathbf{y})



graph data (\mathbf{y}, \mathbf{G})

Corresponding Gaussian MRF



condition on \mathbf{X}
e.g. $L=\{1,3\}, U=\{2\}$

Learning Algorithm

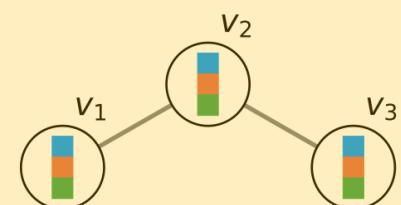
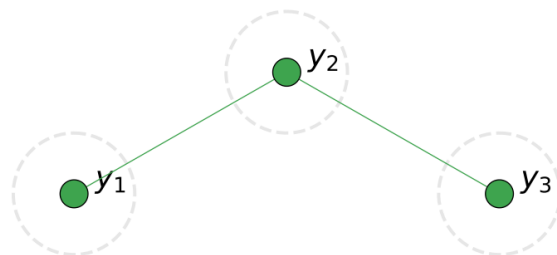
linear regression

$$E[\mathbf{y}_U | \mathbf{X}] = \mathbf{X}_U \boldsymbol{\beta} \quad \boldsymbol{\beta} = (\mathbf{X}_L^T \mathbf{X}_L)^{-1} \mathbf{X}_L^T \mathbf{y}_L$$

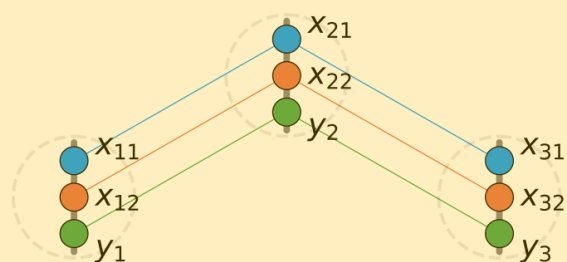
condition on \mathbf{y}_L

label propagation

$$E[\mathbf{y}_U | \mathbf{y}_L] = -(\mathbf{I} + \omega \mathbf{N})_{UU}^{-1} (\mathbf{I} + \omega \mathbf{N})_{UL} \mathbf{y}_L$$



graph data $(\mathbf{X}, \mathbf{y}, \mathbf{G})$



condition on \mathbf{X}

linear GC

further condition on \mathbf{y}_L

$$E[\mathbf{y}_U | \mathbf{X}] = [(\mathbf{I} + \omega \mathbf{N})^{-1} \mathbf{X} \boldsymbol{\beta}]_U$$

residual propagation

$$E[\mathbf{y}_U | \mathbf{X}, \mathbf{y}_L] = \dots$$

change filter

SGC (simple graph convolution)

+nonlinearity

GCN (graph convolution network)

Graph + Features Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) = e^{-\frac{1}{2}(\text{vec}(\mathbf{A}))^\top \mathbf{\Gamma}(\text{vec}(\mathbf{A}))}, \text{ where } \mathbf{\Gamma} = \mathbf{H} \otimes \mathbf{I}_n + \text{diag}(\mathbf{h}) \otimes \mathbf{N}.$$

Now condition on features \mathbf{X} to find labels \mathbf{y} :

Graph + Features Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) = e^{-\frac{1}{2}(\text{vec}(\mathbf{A}))^\top \Gamma (\text{vec}(\mathbf{A}))}, \text{ where } \Gamma = \mathbf{H} \otimes \mathbf{I}_n + \text{diag}(\mathbf{h}) \otimes \mathbf{N}.$$

Now condition on features \mathbf{X} to find labels \mathbf{y} :

$$\begin{aligned} \mathbb{E}[\mathbf{y}|\mathbf{X} = \mathbf{X}] &= -\Gamma_{UU}^{-1} \Gamma_{UL} \text{vec}(\mathbf{X}) \\ &= \left(H_{p+1,p+1} \mathbf{I}_n + h_{p+1} \mathbf{N} \right)^{-1} \left(-\mathbf{H}_{1:p,p+1}^\top \otimes \mathbf{I}_n \right) \text{vec}(\mathbf{X}) \\ &= \left(\mathbf{I}_n + \omega \mathbf{N} \right)^{-1} \mathbf{X} \boldsymbol{\beta}, \text{ where } \omega = \frac{h_{p+1}}{H_{p+1,p+1}} \text{ and } \boldsymbol{\beta} = \frac{-\mathbf{H}_{1:p,p+1}}{H_{p+1,p+1}}. \end{aligned}$$

Graph + Features Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) = e^{-\frac{1}{2}(\text{vec}(\mathbf{A}))^\top \Gamma (\text{vec}(\mathbf{A}))}, \text{ where } \Gamma = \mathbf{H} \otimes \mathbf{I}_n + \text{diag}(\mathbf{h}) \otimes \mathbf{N}.$$

Now condition on features \mathbf{X} to find labels \mathbf{y} :

$$\mathbb{E}[\mathbf{y}|\mathbf{X} = \mathbf{X}] = (\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X} \boldsymbol{\beta}, \text{ where } \omega = \frac{h_{p+1}}{H_{p+1,p+1}} \text{ and } \boldsymbol{\beta} = \frac{-\mathbf{H}_{1:p,p+1}}{H_{p+1,p+1}}.$$

Graph + Features Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) = e^{-\frac{1}{2}(\text{vec}(\mathbf{A}))^\top \Gamma (\text{vec}(\mathbf{A}))}, \text{ where } \Gamma = \mathbf{H} \otimes \mathbf{I}_n + \text{diag}(\mathbf{h}) \otimes \mathbf{N}.$$

Now condition on features \mathbf{X} to find labels \mathbf{y} :

$$\mathbb{E}[\mathbf{y}|\mathbf{X} = \mathbf{X}] = \underbrace{(\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X}} \boldsymbol{\beta}, \text{ where } \omega = \frac{h_{p+1}}{H_{p+1,p+1}} \text{ and } \boldsymbol{\beta} = \frac{-\mathbf{H}_{1:p,p+1}}{H_{p+1,p+1}}.$$

Feature Propagation:

$$\forall u \in V, \mathbf{x}_u^{(0)} = \mathbf{x}_u \text{ and } \mathbf{x}_u^{(t+1)} = (1 - \alpha) \mathbf{x}_u^{(0)} + \alpha d_u^{-1/2} \sum_{v \in N_1(u)} d_v^{-1/2} \mathbf{x}_v^{(t)}.$$

Graph + Features Case

$$\phi(\mathbf{A}|\mathbf{H}, \mathbf{h}) = \frac{1}{2} \sum_{u=1}^n \mathbf{a}_u^\top \mathbf{H} \mathbf{a}_u + \frac{1}{2} \sum_{i=1}^{p+1} h_i \mathbf{A}_i^\top \mathbf{N} \mathbf{A}_i$$

$$\rho(\mathbf{A} = \mathbf{A}|\mathbf{H}, \mathbf{h}) = e^{-\frac{1}{2}(\text{vec}(\mathbf{A}))^\top \Gamma (\text{vec}(\mathbf{A}))}, \text{ where } \Gamma = \mathbf{H} \otimes \mathbf{I}_n + \text{diag}(\mathbf{h}) \otimes \mathbf{N}.$$

Now condition on features \mathbf{X} to find labels \mathbf{y} :

$$\mathbb{E}[\mathbf{y}|\mathbf{X} = \mathbf{X}] = (\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X} \boldsymbol{\beta}, \text{ where } \omega = \frac{h_{p+1}}{H_{p+1,p+1}} \text{ and } \boldsymbol{\beta} = \frac{-\mathbf{H}_{1:p,p+1}}{H_{p+1,p+1}}.$$

Algorithm (Linear Graph Convolution / LGC):

- 1) Do feature propagation to compute $\bar{\mathbf{X}} = (\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X}$.
- 2) Fit $\boldsymbol{\beta}$ directly via linear regression on $(\bar{\mathbf{X}}_L, \mathbf{y}_L)$.

Graph + Features + Known Labels Case

Condition on both features \mathbf{X} and known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U .

$$\mathbb{E}[\mathbf{y}_U | \mathbf{X} = \mathbf{X}, \mathbf{y}_L = \mathbf{y}_L] = \dots$$

Algorithm (LGC with Residual Propagation):

Graph + Features + Known Labels Case

Condition on both features \mathbf{X} and known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U .

$$\mathbb{E}[\mathbf{y}_U | \mathbf{X} = \mathbf{X}, \mathbf{y}_L = \mathbf{y}_L] = \dots$$

Algorithm (LGC with Residual Propagation):

- 1) Do feature propagation to compute $\bar{\mathbf{X}} = (\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X}$.
- 2) Fit $\boldsymbol{\beta}$ directly via linear regression on $(\bar{\mathbf{X}}_L, \mathbf{y}_L)$.

Graph + Features + Known Labels Case

Condition on both features \mathbf{X} and known labels \mathbf{y}_L to find unknown labels \mathbf{y}_U .

$$\mathbb{E}[\mathbf{y}_U | \mathbf{X} = \mathbf{X}, \mathbf{y}_L = \mathbf{y}_L] = \dots$$

Algorithm (LGC with Residual Propagation):

- 1) Do feature propagation to compute $\bar{\mathbf{X}} = (\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X}$.
- 2) Fit $\boldsymbol{\beta}$ directly via linear regression on $(\bar{\mathbf{X}}_L, \mathbf{y}_L)$.
- 3) Compute the regression residuals on known labels: $\bar{\mathbf{r}}_L = \mathbf{y}_L - \bar{\mathbf{X}}_L \boldsymbol{\beta}$.
- 3) Do “residual propagation” of $\bar{\mathbf{r}}_L$ to estimate $\bar{\mathbf{r}}_U$.
- 4) Modify the LGC predictions: return $\bar{\mathbf{X}}_U \boldsymbol{\beta} + \bar{\mathbf{r}}_U$.

Connections to Other Graph Convolution

Linear Graph Convolution (LGC):

$$\mathbf{y}_{LGC} = (\mathbf{I}_n + \omega \mathbf{N})^{-1} \mathbf{X} \boldsymbol{\beta} = (1 - \alpha)(\mathbf{I} + \alpha \mathbf{S} + \alpha^2 \mathbf{S}^2 + \dots) \mathbf{X} \boldsymbol{\beta}.$$

Simplified Graph Convolution (SGC):

$$\mathbf{y}_{SGC} = \tilde{\mathbf{S}}^K \mathbf{X} \boldsymbol{\beta}.$$

Graph Convolutional Networks (GCN):

$$\begin{aligned} \mathbf{y}_{GCN} &= \sigma(\tilde{\mathbf{S}} \dots \sigma(\tilde{\mathbf{S}} \mathbf{X} \boldsymbol{\Theta}^{(1)}) \dots \boldsymbol{\Theta}^{(K)}) \boldsymbol{\beta} \\ &= \tilde{\mathbf{S}}^K \mathbf{X} \boldsymbol{\beta}' \text{ if } \sigma(x) = x. \end{aligned}$$

A Unifying Generative Model for Graph Learning Algorithms

